



# HEIDENHAIN

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Preliminary  
Product Information

## EIB 2391 S

External Interface Box

September 2011

# EIB 2391 S

## External Interface Box

- Input: HEIDENHAIN encoders with EnDat22 interface
- Output: DRIVE-CLiQ interface

### Requirements of the encoder with EnDat22 interface at the input

The EIB supports connection of the following encoders (with or without functional safety) to the DRIVE-CLiQ interface:

- Absolute linear encoders (e.g. LC 183, LC 483, LC 115, LC 415, LC 2xx, LIC 4000)
- Absolute singleturn encoders and angle encoders (e.g. RCN 2xxx, RCN 5xxx, RCN 8xxx, ECN 1325, ROC 425, ROC 1023)
- Absolute multiturn encoders (e.g. EQN 1337, EQN 437, ROQ 437, ROQ 1035, ECN 125)

In principle, it is possible to connect further encoders to the EnDat22 interface depending, however, on the firmware level of the EIB. For more information, please contact HEIDENHAIN.

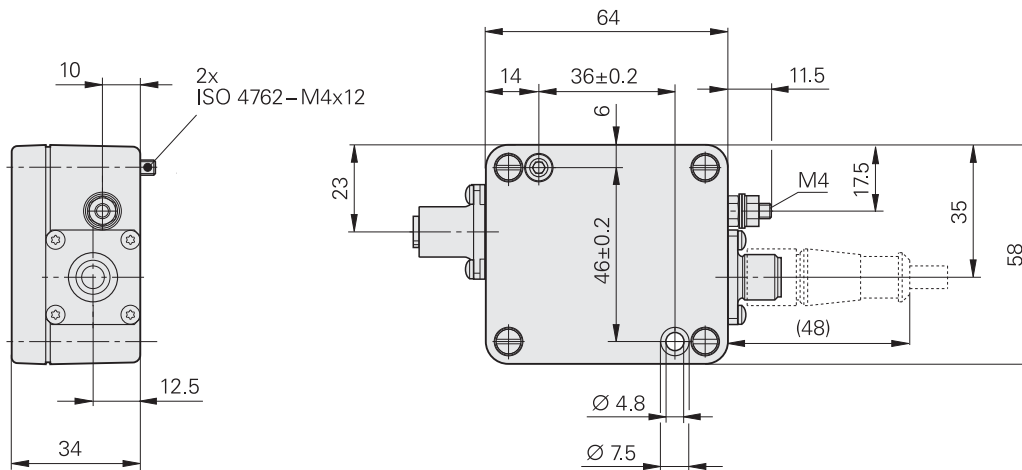
After switch-on, the EIB tests various characteristics of the connected EnDat encoder and automatically adapts to the encoder. If the encoder doesn't fulfill the specific requirements, a corresponding error message is transmitted through the DRIVE-CLiQ interface. The encoder has meet the following requirements:

- EnDat 2.2 mode commands must be supported
- EnDat clock frequency  $\geq 8$  MHz
- Must be adjustable to a shortened recovery time of 1.25 to 3.75  $\mu$ s
- Ascending position value with clockwise rotation of the encoder (viewed from flange side) or traverse to the right on linear encoders (with respect to the ID label).
- Multiturn rotary encoders with binary line count
- Linear encoders with measuring steps in nanometer (nm)

### Functional safety

The characteristics regarding functional safety are substantially determined by the connected encoder and the subsequent electronics (if necessary, contact the manufacturer; the EIB essentially passes on the characteristics of the encoder). The EIB can be used in safety-related applications only if the connected encoder supports functional safety.

The Safe Position is primarily determined by the connected encoder. Further deviations of the Safe Position may occur in the subsequent electronics after the position value comparison. Please contact the manufacturer of the subsequent electronics for further information.



| Specifications                                       | EIB 2391 S   |
|--|--|
| <b>Functional safety</b> <sup>1)</sup>               | Depending on the connected encoder and subsequent electronics, suited for applications up to <ul style="list-style-type: none"> <li>• SIL 2 according to EN 61508 (further basis for testing: EN 61800-5-2)</li> <li>• Category 3 PL d according to EN ISO 13849-1:2008</li> </ul> |
| PFH  | To be determined   |
| Safe position <sup>2)</sup>                          | t.b.d. (without the connected encoder)   |
| <b>Input</b>   |  |
| Interface  | EnDat 2.2 interface  |
| Ordering designation                                 | EnDat22  |
| Electrical connection                                | M12 connector (female), 8-pin  |
| Power supply of encoder                              | 5.1 V DC $\pm$ 3%, max. 2000 mW  |
| Cable length   | $\leq$ 20 m <sup>3)</sup>  |
| <b>Output</b>  |  |
| Interface  | DRIVE-CLiQ   |
| Ordering designation                                 | DQ01   |
| Electrical connection                                | M12 connector (male), 8-pin  |
| Cable length   | $\leq$ 100 m <sup>4)</sup>   |
| <b>Power supply</b>                                  | 24 V DC +20 % / -15 %  |
| <b>Power consumption</b>                             | $\leq$ 1500 mW at 24 V DC (without connected encoder)  |
| <b>Operating temperature</b>                         | 0 °C to 70 °C  |
| <b>Storage temperature</b>                           | -30 °C to 70 °C  |
| <b>Vibration</b> 55 to 2000 Hz<br><b>Shock</b> 11 ms | 100 m/s <sup>2</sup> (IEC 60068-2-6)<br>200 m/s <sup>2</sup> (IEC 60068-2-27)  |
| <b>Protection</b>                                    | IP 65  |
| <b>Weight</b>  | Approx. 180 g  |

<sup>1)</sup> Preliminary data

<sup>2)</sup> Further deviations may occur in the subsequent electronics after the position value comparison (contact the manufacturer of the subsequent electronics)


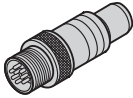



<sup>3)</sup> With HEIDENHAIN cable;  $P_{\text{encoder}} \leq 1500 \text{ mW}$ ; greater cable lengths upon request ( $U_{\text{encoder}}$  !)

<sup>4)</sup> Depending on the output cable


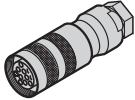
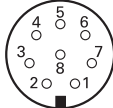

The EIB 2391 S is planned to become available beginning in the 2nd quarter of 2012

# Interfaces

## Pin layout of the EIB input

|  |                      |                             |             |                  |                          |             |              |              |
|--|----------------------|-----------------------------|-------------|------------------|--------------------------|-------------|--------------|--------------|
| <i>Mating connector</i><br><b>8-pin coupling M12</b>    |                      |                             |             |                  |                          |             |              |              |
|  | Power supply         |                             |             |                  | Absolute position values |             |              |              |
|    | <b>8</b>             | <b>2</b>                    | <b>5</b>    | <b>1</b>         | <b>3</b>                 | <b>4</b>    | <b>7</b>     | <b>6</b>     |
| <b>EnDat</b>   | <b>U<sub>P</sub></b> | <b>Sensor U<sub>P</sub></b> | <b>0V</b>   | <b>Sensor 0V</b> | <b>DATA</b>              | <b>DATA</b> | <b>CLOCK</b> | <b>CLOCK</b> |
|    | Brown/Green          | Blue                        | White/Green | White            | Gray                     | Pink        | Violet       | Yellow       |

## Pin layout of the EIB output



|   |                      |           |                          |             |             |             |            |          |
|---|----------------------|-----------|--------------------------|-------------|-------------|-------------|------------|----------|
| <i>Mating connector</i><br><b>8-pin connector M12</b>    |                      |           |                          |             |             |             |            |          |
|   | Power supply         |           | Absolute position values |             |             |             | Other data |          |
|    | <b>1</b>             | <b>5</b>  | <b>3</b>                 | <b>4</b>    | <b>7</b>    | <b>6</b>    | <b>2</b>   | <b>8</b> |
|   | <b>U<sub>P</sub></b> | <b>0V</b> | <b>RX_P</b>              | <b>RX_N</b> | <b>TX_P</b> | <b>TX_N</b> | /          | /        |

**Cable shield** connected to housing; **U<sub>P</sub>** = power supply voltage

**Sensor:** The sensor line is connected in the encoder with the corresponding power line.

Vacant pins or wires must not be used!

## Cables

| Cable for encoder connection  |   | ID         |
|---|---|------------|
| Complete with 8-pin M12 connector (female) and 8-pin M12 coupling (male)              |  | 368 330-xx |
| Complete with right-angled 8-pin M12 connector (female) and 8-pin M12 coupling (male) |  | 373 289-xx |

The cables for connection to DRIVE-CLiQ are available from the manufacturer of the subsequent electronics

# HEIDENHAIN

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### Related documents

- Technical Information: *EnDat*
- Technical Information: *Safety-Related Position Measuring Systems*
- Catalog: *Rotary Encoders*
- Catalog: *Position Encoders for Servo Drives*
- Catalog: *Absolute Angle Encoders with Optimized Scanning*
- Catalog: *Linear Encoders for Numerically Controlled Machine Tools*